

Contact Type Radar Level Transmitter

A practical guide to contact type radar level transmitter, covering the reader intent, the relationship to contact type radar level transmitter, key evaluation criteria, common risks, and the information the intended project audience should confirm before taking the next step.



level-measurement

Main topic: Radar Level Meters

<https://www.level-meters.com/products/radar-level-meters/>

In the field of industrial process control, selecting the correct instrumentation for level measurement is critical for operational efficiency and safety. Among the various technologies available, the contact type radar level transmitter, commonly referred to as Guided Wave Radar (GWR), has established itself as a versatile and robust solution for challenging environments. Unlike non-contact systems that broadcast signals through the air, these instruments utilize a physical probe to guide electromagnetic pulses directly to the process media.

As part of the broader family of Radar Level Meters, contact type transmitters offer unique advantages in applications where foam, dust, or vapor might interfere with traditional non-contact signals. This guide explores the principles, selection criteria, and installation requirements for contact type radar technology in modern industrial settings.

1. Measurement Principle: Time Domain Reflectometry (TDR)

The fundamental technology behind a contact type radar level transmitter is Time Domain Reflectometry (TDR). This method is analogous to the technology used to locate breaks in underground communication cables.

The Measurement Cycle

1. **Pulse Generation:** The transmitter's electronics generate low-energy micro-pulses of electromagnetic energy (typically in the gigahertz range).
2. **Guided Propagation:** These pulses are transmitted along a physical probe (a rod, cable, or coaxial tube) that acts as a waveguide.
3. **Reflection:** When the pulse reaches the surface of the medium being measured, a portion of the energy is reflected back toward the electronics. This reflection occurs due to the change in the dielectric constant (ϵ_r) between the air/gas space and the process medium.
4. **Signal Processing:** The instrument measures the "time of flight"—the interval between the pulse emission and the receipt of the echo. Since the speed of light is constant, the distance to the surface is calculated with high precision.

Because the signal is concentrated along the probe rather than dispersed in a cone, the signal-to-noise ratio is significantly higher than that of non-contact radar. This makes it particularly effective for media with low dielectric constants or in tanks with complex internal geometries.

| 2. Probe Selection and Configuration

The performance of a contact type radar level transmitter is heavily dependent on the type of probe selected. Engineers must match the probe geometry to the physical properties of the medium and the vessel's dimensions.

| Single Rod or Cable Probes

Single-element probes are the most common and easiest to clean. They are ideal for liquids with high dielectric constants (such as water-based solutions) and are less prone to media build-up. However, they are more sensitive to electromagnetic interference from tank walls or internal obstructions if placed too close.

| Twin Rod or Double Cable Probes

These probes consist of two parallel elements. The electromagnetic field is concentrated between the two conductors, providing a stronger signal than single-rod versions. They are often used for liquids with lower dielectric constants or in applications where the transmitter must be installed near a wall.

| Coaxial Probes

Coaxial probes consist of a central rod inside an outer perforated tube. This design offers the highest signal efficiency because the electromagnetic pulse is entirely contained within the tube. Coaxial probes are immune to tank internal obstructions and are the gold standard for measuring low-dielectric fluids like liquefied gases or oils. They are also excellent for turbulent surfaces, as the outer tube acts as a stilling well.

3. Technical Selection Table

The following table provides a general reference for selecting probe types based on common process conditions.

Feature	Single Rod/Cable	Twin Rod/Cable	Coaxial Probe
Max Range	Up to 30m (Cable)	Up to 30m	Up to 6m
Dielectric Constant (\$\epsilon_r\$)	\$\epsilon_r \ge 1.9\$	\$\epsilon_r \ge 1.4\$	\$\epsilon_r \ge 1.1\$
Viscous/Caking Media	Excellent	Poor	Not Recommended
Turbulence Resistance	Moderate	Good	Excellent
Internal Obstructions	Sensitive	Moderate	Insensitive
Cleaning Ease	High	Moderate	Low

4. Installation Considerations and Best Practices

To ensure the accuracy of Radar Level Meters using guided wave technology, several installation parameters must be strictly observed.

Mounting Position

The transmitter should be mounted away from the tank inlet to avoid direct contact with the product flow, which could cause mechanical damage or false readings. For single-rod probes, a minimum distance of 300 mm (approx. 12 inches) from the tank wall is generally required to prevent signal interference.

| The "Dead Zone"

Every contact type radar level transmitter has an upper and lower "dead zone" (also known as the blocking distance). In these areas, the instrument cannot provide accurate measurements.

Upper Dead Zone: Typically ranges from 50 mm to 500 mm depending on the probe type and medium. This is where the pulse is launched.

Lower Dead Zone: Usually 50 mm to 100 mm at the tip of the probe, where the signal may be lost or distorted as it reaches the end of the waveguide.

| Nozzle Geometry

The mounting nozzle should be as short and wide as possible. If the nozzle is too narrow or long, it can create parasitic reflections that interfere with the initial signal pulse, especially for single-rod configurations.

| Mechanical Stress

In tall silos or tanks with heavy agitation, the lateral forces on the probe can be significant. Cable probes should be used for heights exceeding 6 meters to allow for flexibility. In some cases, the cable must be anchored to the bottom of the tank; however, a tensioning weight or spring must be used to account for thermal expansion and contraction.

| 5. Advanced Applications: Interface Measurement

One of the primary reasons engineers specify a contact type radar level transmitter is its ability to measure the interface between two liquids, such as oil and water.

When a pulse travels through a low-dielectric upper layer (e.g., oil, $\epsilon_r \approx 2.0$), part of the energy reflects off the surface. The remaining energy continues through the oil and reflects off the interface of the high-dielectric lower layer (e.g., water, $\epsilon_r \approx 80$). By analyzing both echoes, the transmitter can provide the total level and the interface level simultaneously. This is a critical capability in separators and settling tanks within the oil and gas and chemical industries.

| 6. Limitations and Potential Risks

While highly reliable, GWR technology is not a universal solution. Engineers should be aware of the following limitations:

Media Build-up: While GWR handles some coating better than non-contact radar, excessive build-up of conductive or viscous material between twin rods or inside a coaxial tube will cause signal attenuation and measurement errors.

Corrosion and Compatibility: Since the probe is in direct contact with the process, the material (e.g., 316L Stainless Steel, Hastelloy, or PTFE coating) must be chemically compatible with the media.

Mechanical Obstructions: If a probe touches the tank wall or an internal ladder due to agitation, it will create a false level signal at that point.

| 7. Frequently Asked Questions (FAQ)

Q: Can a contact type radar level transmitter measure solids and powders?

A: Yes. Cable-style GWR is frequently used in silos for powders and granulates. However, the pull-down forces exerted by the solid material on the cable must be calculated to prevent damage to the tank roof or the transmitter sensor.

Q: How does foam affect the measurement?

A: GWR is generally unaffected by light, airy foam. If the foam is dense and conductive, the radar pulse will reflect off the top of the foam. If the foam is non-conductive, the pulse will pass through it and reflect off the liquid surface, providing an accurate liquid level.

Q: Does the tank pressure or temperature affect the accuracy?

A: Within the rated limits of the sensor, pressure and temperature have a negligible effect on the speed of the electromagnetic pulse. This makes GWR superior to ultrasonic sensors, which require compensation for changes in the speed of sound due to gas density variations.

Q: Is calibration required on-site?

A: Most modern transmitters come pre-configured based on the ordered probe length. On-site calibration usually involves simple "zero" and "span" adjustments or entering the tank height and dielectric constant of the medium via a local display or HART communicator.

| Conclusion

The contact type radar level transmitter represents a robust engineering choice for complex level and interface measurement tasks. By guiding the signal directly to the media, it overcomes many of the environmental challenges that hinder other technologies. When selecting a device from a range of Radar Level Meters, engineers must prioritize probe material compatibility, vessel geometry, and the dielectric properties of the process medium to ensure long-term reliability and precision in their automation systems.